



## VLADIMIR VASIL'YEVICH BELETSKII (on the occasion of his 70th birthday)†



On 2nd May 2000, one of the founders of the modern mechanics of space flight, Doctor of Physical and Mathematical Sciences, Professor and Corresponding Member of the Russian Academy of Sciences, Vladimir Vasil'yevich Beletskii, celebrated his 70th birthday.

The scientific interests of Professor Beletskii are multifaceted. He is credited with formulating and solving problems of the mechanics of rotational motion of spacecraft and the theory of space tether systems. His investigations of non-linear problems of celestial mechanics, the dynamics of biped robots, deterministic chaos in applied problems of solid-state dynamics and dynamical billiards have also received world-wide recognition.

He was born in Irkutsk. His childhood was spent in this town and in villages on the banks of the Angara and Baikal. In 1949, he left secondary school with a Gold Medal and the Honorary Certificate of the Central Committee of the Leninist Young Communist League, a fairly rare award in those days, related primarily to the active work of pupils in the restoration of Smolensk. In the same year, he entered the Mechanics and Mathematics Faculty of Moscow State University (MGU). The brilliant professors of mechanics and mathematics of those years instilled in him a passion for scientific research that has lasted to this day. His diploma, carried out under the supervision of Professor A. A. Kosmodem'yanskii, was published 20 years later, but lost none of its relevance during this time.

Graduating from the MGU in 1954 with distinction, he was assigned work in the Department of Applied Mathematics of the V. A. Steklov Mathematical Institute of the Academy of Sciences of the USSR; the Department was founded by M. V. Keldysh (now the M. V. Keldysh Institute of Applied Mathematics of the Russian Academy of Sciences). This determined his scientific career as one of the group of seven brilliant scientists of the world renowned School of Space Flight Dynamics, founded by Keldysh and Okhotsimskii.

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At the end of the 1950s and the beginning of the 1960s, he carried out a cycle of investigations of unique innovation and volume into the motion of artificial satellites about a centre of mass under the action of the disturbing moments arising in flight, thereby opening up a new area in solid-state dynamics.

His first investigations were already well known and had gained the recognition of specialists in the field. For example, on 14th September 1956, Keldysh, in his paper (at that time, classified) at a session of the Praesidium of the USSR Academy of Sciences, on the stability of relative equilibrium of a satellite in orbit, remarked "... This most interesting problem of solid-state mechanics has been solved entirely by my young colleague V. V. Beletskii in the Department of Applied Mathematics".

The results of these investigations were summed up in a monograph of 1965 which, having been translated into English, is to this day a reference book for specialists. The main results of this group of studies are as follows. The theorem on the conditions of stability of the relative equilibrium of a satellite in a gravitational field was proved. The theory of the vibrations of a satellite in an elliptic orbit under the action of the moment of the gravity gradient was developed. The problem was formulated and the theory was developed concerning the evolution of rotation of satellites under the influence of disturbing moments caused by the gravity gradient and the influence of the Earth's magnetic field, the atmosphere and light pressure forces. This theory was used to describe the motion of many specific satellites. The surprisingly fine evolution of the rotation of satellites of the Proton and Prognoz type was discovered, for example. An investigation was made into the possibility of stabilization along a magnetic line of force of a satellite possessing its own magnetic moment, which was used, among many other things, to describe the motion of small spacecraft in the Active and Apex international projects. He was the first to formulate and examine the problem of the dynamics of "coupled" orbital bodies as a system with a releasing link. This problem was used as a model of the dynamics of projected and now launched orbital tether systems. The impact nature of connecting up in these systems can lead to chaotization of motions ("dynamical billiards").

During those years, he was the first world-wide to formulate the general problem of determining the actual orientation of a satellite and defining more accurately the parameters of the disturbing moments acting on it from the measurement data provided by orientation sensors onboard. He developed and used an effective procedure for solving this problem (the third Soviet artificial satellite, the Proton satellite). This approach is being used successfully to this day.

He obtained fundamental results in investigating the evolution of the orbit of a spacecraft under a small disturbing acceleration. He obtained approximate analytical solutions of the problem of the spiral acceleration of a satellite with a low-thrust engine with a circular to parabolic orbit and the problem of the optimum interplanetary flight of a low-thrust spacecraft.

These investigations are of great practical importance in relation to the launching in recent years of experimental spacecraft with ion-plasma jet engines and the prospects of using solar panels.

Possessing a fertile imagination and a well-developed sense of humour, from time to time he sets, solves and publishes problems that could be classified as science fiction were it not for the mathematically rigorous proofs of the feasibility of these proposals that he provides. Thus, he thought up the "gravilet" – a method of manoeuvring a spacecraft in a gravitational field without loss of mass on board merely by changing the dimensions or orientation of the spacecraft. He suggested that a space station in the neighbourhood of the libration point of the Earth–moon system could be stabilized (to prevent it flying away) by tying it to the moon with a tether (60 000 km long!). Analysing his theorem of the stability of a body (satellite) in orbit in a gravitational field, he obtained the constraints on the size of the body: for example, a dumbbell-shaped satellite is stable if its half-length does not exceed the radius of the orbit of its centre of mass by more than a factor of  $\sqrt{3}-\sqrt{2}$ . Otherwise it is unstable. Another result of this kind showed that a certain ring of flexible thread around the Earth is stable at a certain ring radius and law of stretchability. This law of stretchability is quite distinct from Hooke's law, according to which the ring is unstable.

From the start of the 1970s onwards, he carried out a group of investigations on non-linear problems of the dynamics of the rotational motion of satellites and planets taking into account existing resonances in their orbital and rotational motion, and also the influence of the dissipation of energy (the tidal effect) on the formation of the present pattern of the rotation of the planets, taking the probabilities of trapping in existing resonances into account. We will note here only one remarkable fundamental result: the creation of the resonance theory of "generalized Cassini laws" of the rotation of the planets, which gives a rigorous validation of Cassini's empirical laws of rotation of the moon (1693) and thereby closes a 300 year old problem which occupied Lagrange and Laplace.

His remarkable scientific achievements include the monograph *Essays on the Motion of Cosmic Bodies* (2nd edition published in 1977), which has been translated into many languages. In this work he combined what had hitherto seemed incompatible – a mathematically rigorous presentation of the analysis of the

finest problems in space dynamics (most of which belong to the author) in the form of an engrossing literary composition. This, in the words of V. I. Arnol'd and Ya. B. Zel'dovich, was the "start of a new style of scientific literature".

He has published over 200 scientific works, including 10 monographs that have been reprinted at home and abroad. His works are easy to read because they are written with a regard for the reader and combine a rigour of analysis and an excellent style of presentation.

He has fruitfully combined his many years of scientific activity at the V. V. Keldysh Institute of Applied Mathematics with teaching, being a professor in the Department of Theoretical Mechanics of the Mechanics and Mathematics Faculty of MGU. Among his students there have been over 25 masters and doctors of sciences. The dissertations prepared under his supervision are noted for the innovative nature of the problems discussed, the originality of results and their practical significance.

His scientific achievements have been recognized both in Russia and abroad. He is a corresponding member of the Russian Academy of Sciences, a member of the National Committee on Theoretical and Applied Mechanics, a member of the International Academy of Astronautics, a winner of the von Humboldt prize (Germany) and a winner of the F. A. Tsander prize of the Russian Academy of Sciences. Among his awards is the M. V. Keldysh medal of the USSR Federation of Astronautics.

Many years ago, a remarkable Irkutsk doctor saved his life but was unable to give him back his hearing. Professor Beletskii possesses a rare quality: he is able to listen to people and is ready to come to the aid of anyone in need of help. He does not confine himself to his scientific interests but also loves poetry and painting, nature, travel and socializing, where he always exhibits his friendliness, humour and love of life.

The editorial staff and editorial board of *Applied Mathematics and Mechanics* and his students and friends wish him good health, a long life and further scientific achievements.

#### A LIST OF THE SCIENTIFIC PUBLICATIONS BY V. V. BELETSKII

1956

The vertical lift of a point of variable mass. *Prikl. Mat. Mekh.* **20**, 4, 559–560.

1957

The integrability of the equations of motion of solids about a fixed point under the action of a central Newtonian force field. *Dokl. Akad. Nauk SSSR* **113**, 2, 287–290.

Some problems of the motion of a solid in a Newtonian force field. *Prikl. Mat. Mekh.* **21**, 6, 749–758.

1958

The motion of an artificial satellite about the centre of mass. In *Artificial Satellites*, Izd Akad Nauk SSSR, Moscow, 1, 25–43.

1959

The libration of a satellite. In *Artificial Earth Satellites*. Izd Arad Nauk SSSR, Moscow, 3, 13–31.

The observation of an artificial satellite by the expectation method. In *Artificial Earth Satellites*, Izd Akad Nauk SSSR, Moscow, 3, 47–53 (together with V. M. Vakhnin).

1960

Libration of an artificial Earth satellite. In *10th Int. Astronaut. Congr.*, London, 1959, Vienna, Vol. 2, 848–849.

The libration of a satellite. *J. R. Astronaut. Soc.*, **64**, 599, 711.

1961

Classification of the motions of an artificial Earth satellite about the centre of mass. In *Artificial Earth Satellites*, Izd Arad Nauk SSSR, Moscow, 6, 11–32.

The rotation and orientation of the third Soviet artificial satellite. In *Artificial Earth Satellites*. Izd Akad Nauk SSSR, Moscow, 7, 32–55 (together with Yu. V. Zonov).

## 1962

The orbit of an equatorial Earth satellite. In *Artificial Earth Satellites*. Izd Akad Nauk SSSR, Moscow, 13, 53–60.

The classification of artificial Earth satellite paths about the mass centre. *Planet and Space Sci.* **9**, 1, 47–65.

## 1963

Some problems of the motion of artificial satellites in about the centre of mass. In *Problems of the Motion of Artificial Celestial Bodies*. Izd Arad Nauk SSSR, Moscow, 218–228.

Libration of a satellite in an elliptic orbit. In *Artificial Earth Satellites*, Izd Akad Nauk SSSR, Moscow, 16, 46–56.

Some problems of the translational–rotational motion of a solid in a Newtonian force field. In *Artificial Earth Satellites*, Izd Akad Nauk SSSR, Moscow, 16, 68–93.

The use of an Earth-oriented satellite for solar research. In *Artificial Earth Satellites*, Izd Akad Nauk SSSR, Moscow, 16, 94–123 (together with D. Ye. Okhotsimskii).

The evolution of the rotation of a dynamically symmetrical satellite. *Kosmich. Issled.* **1**, 3, 339–386.

A case of the motion of a solid about a fixed point in a Newtonian field. *Prikl. Mat. Mekh.* **27**, 1, 175–178.

Problems of motion of the Earth's satellites about the center of mass. In *Proc. 14th Int. Astronaut. Congr.*, Paris, 1963, 215–234 (together with V. A. Sarychev).

The orbit of an equatorial Earth satellite. *Planet and Space Sci.* **11**, 5, 553–560.

Some problems of motion of artificial satellites about the centre of mass. In *Dynamics of Satellites. Symp.*, Paris, 1962 Springer, Berlin, 158–167.

The libration of a satellite on an elliptic orbit. In *Dynamics of Satellites. Symp.*, Paris, 1962 Springer, Berlin, 219–230.

## 1964

Interplanetary flights with constant-power engines. *Kosmich. Issled.* **2**, 3, 360–391 (together with V. A. Yegorov).

Acceleration of a spacecraft in the sphere of action of a planet. *Kosmich. Issled.* **2**, 3, 392–407 (together with V. A. Yegorov).

Trajectories of space flights with a constant vector of jet engine acceleration. *Kosmich. Issled.* **2**, 3, 408–413.

Motion of an artificial satellite about the centre of mass. In *Compendium of Lectures given at Moscow State University in 1962–1963*, Dzerzhinskii Academy.

## 1965

*Motion of an Artificial Satellite about the Centre of Mass*, Nauka, Moscow, 1965.

Analysis of the trajectories of interplanetary flights with constant-power engines. *Kosmich. Issled.* **3**, 4, 507–522 (together with V. A. Yegorov and V. G. Yerшов).

## 1966

*Motion of an Artificial Satellite about its Center of Mass*. Israel Program for Scientific Translations, Jerusalem.

*Motion of an Artificial Satellite about its Centre of Mass*. Oldbourne Press, London.

*Motion of an Artificial Satellite about its Center of Mass*. NASA Techn. Transl. TTF-429.

1967

*Determination of the Orientation of Artificial Satellites from Measurement Data. Part 1. Method*, Izd Inst. Prikl Math. Akad Nauk SSSR, Moscow (together with V. V. Golubkov, I. G. Khatskevich and Ye. A. Stepanova).

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Determination of the orientation and rotation of artificial satellites from measurement data. *Kosmich. Issled.* 5, 5, 686–702 (together with V. V. Golubkov, E. K. Lavrovskii, S. I. Trushin and I. G. Khatskevich).

Limits of librations of a triaxial satellite in a gravitational field. *Prikl. Mat. Mekh.* 31, 6, 1104–1107.

1968

*Determination of the Orientation of Artificial Satellites from Measurement Data. Part 2. Results*, Izd Inst Prikl Math. Akad Nauk SSSR, Moscow (together with V. V. Golubkov, I. G. Khatskevich and Ye. A. Stepanova).

Motion of a pulsating system in a gravitational field. *Kosmich. Issled.* 6, 2, 304–306 (together with M. Ye. Giverts).

Some advances in space ballistics. *Collection of Scientific and Procedural Papers on Theoretical Mechanics*. Vysshaya Shkola, Moscow, No. 1, 37–53.

On determination of atmosphere parameters from drag data of the satellite Proton-2, orientation being taken into account. Paper read at the 12th COSPAR Planetary Meeting Prague, (together with M. Ya. Marov and G. I. Zmiyevskaya).

Analysis of the rotation and orientation of the Proton-2 satellite. In *Proc. 18th Int. Astronaut. Congr.*, Belgrade, 1967, Pergamon Press, London, Vol. 1, 151–161 (together with V. V. Golubkov, Ye. A. Stepanova and I. G. Khatskevich).

1969

Mechanics of space flight. In *50 years of Mechanics in the USSR*. Nauka, Moscow, 265–319 (together with G. L. Grozdovskii, D. Ye. Okhotsimskii et al.).

The results of determination of orientation from onboard measurement data. In *Evolution d'Attitude et Stabilisation des Satellites*. Paris, 25–59 (together with V. V. Golubkov, Ye. A. Stepanova and I. G. Khatskevich).

The relative motion of two tethered bodies in orbit. *Kosmich. Issled.* 7, 3, 377–384 (together with Ye. T. Novikova).

Results of determining the orientation of the Proton-2 satellite and a description of its motion about the centre of mass. *Kosmich. Issled.* 7, 4, 522–533 (together with V. V. Golubkov, Ye. A. Stepanova and I. G. Khatskevich).

The relative motion of two tethered bodies in orbit. II. *Kosmich. Issled.* 7, 6, 827–840.

1970

Assessment of the nature of interaction of aerodynamic flow with a satellite from an analysis of the motion of the Proton-2 satellite about the centre of mass. *Kosmich. Issled.* 8, 2, 206–217.

Determination of atmospheric parameters from data on the deceleration of the Proton-2 satellite taking its orientation into account. *Kosmich. Issled.* 8, 6, 889–895 (together with G. I. Zmiyevskaya and M. Ya. Marov).

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The relative motion of two tethered bodies in orbit. In *Proc. 5th Int. Conf. on Non-linear Vibrations*, Kiev, 1970. Izd Inst Mat. Akad Nauk UKSSR, Kiev, 49–54 (together with Ye. T. Novikova). *Gravilet. Tekhnika – Molodezhi*, 3, 26–28

1971

The optimum placing of an artificial Earth satellite into a gravitationally stable position. *Kosmich. Issled.* 9, 3, 366–375.

The spatial motion of two tethered bodies in orbit. *Izv. Akad. Nauk SSSR. MTT*, 5, 23–28 (together with Ye. T. Novikova).

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Cassini's laws. Preprint No. 79, Institute of Applied Mathematics, USSR Acad. Sci., Moscow.

## 1972

Resonances in the rotation of celestial bodies and Cassini's laws. In *Abstracts of Papers Read at the 13th Int. Congr. on Theoretical and Applied Mechanics*. Nauka, Moscow, 32–33.

*Essays on the Motion of Cosmic Bodies*. Nauka, Moscow, 1972.

*Principles of the Theory of Spacecraft Flight* Eds G. S. Narimanov and M. K. Tikhonravov, Mashinostroyeniye, Moscow (together with a large team of authors):

Stability of rapid rotations of an axisymmetrical satellite in a gravitational field. *Dokl. Akad. Nauk SSSR* 203, 1, 50–53 (together with A. P. Torzhevskii).

Resonance rotation of celestial bodies and Cassini's laws. *Celest. Mech.* 6, 3, 356–378.

## 1973

Some results of processing observations of the 1958-b satellite. In *Observations of Artificial Earth Satellites*. Prague, No. 12, 228–248 (together with V. M. Grigorevskii et al.).

Der Einfluss der aerodynamischen Momente auf die Drehbewegung der Proton-Satelliten. *Z. Flugwissenschaft*, 21, 2, 55–63.

Assessment of the parameters of a mirror diffusion model of an image from the motion relative to the centre of mass of Proton-series satellites. *Kosmich. Issled.* 11, 2, 171–179 (together with M. L. Bronshtein and G. A. Propirnyi).

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Magnetic-gravitational stabilization of a satellite. *Izv. Akad. Nauk SSSR, MTT*, 4, 22–32 (together with A. A. Khentov).

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Dynamics of rapid rotations. *Nauch. Tr. In-ta Mekhaniki MGU*, 29, 97–118.

Description of plane trajectories of space flights with a constant vector of rocket acceleration. In *Modern Problems of Celestial Mechanics and Astrodynamics*, Senior Ed. G. A. Chebotarev. Nauka, Moscow, 213–225.

Plane linear models of biped walking. Preprint No. 95, Institute of Applied Mathematics, USSR Acad. Sci., Moscow, 1973.

## 1974

Resonances in the rotation of celestial bodies and generalized Cassini laws. In *Solid-State Mechanics*. Naukova Dumka, Kiev, No. 6, 50–69 (together with S. I. Trushin).

Stability of generalized Cassini laws. In *Solid-State Mechanics*. Naukova Dumka, Kiev, No. 6, 69–86 (together with S. I. Trushin).

Influence of the instability of an axisymmetrical body entering the atmosphere on the motion of its centre of mass. *Kosmich. Issled.* 12, 6, 803–810 (together with B. V. Sekhno).

Dynamics of biped walking. Preprint No. 32, Institute of Applied Mechanics, USSR Acad. Sci. Moscow, 1974.

## 1975

*Motion of a Satellite about the Centre of Mass in a Gravitational Field*, MGU, Moscow, 1975.

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The rotational motion of a satellite and atmospheric density determination. In *Satellite Dynamics. Sympos.*, Sao-Paulo, Brazil, 1974, Ed. G. E. O. Giagaglia. Springer, Berlin, 233–279 (together with V. M. Grigorevskii and S. Ya. Kolesnik).

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The dynamics of biped walking. II. *Izv. Akad. Nauk SSSR. MTT*, 4, 3–13.

Steady rotations of a magnetized satellite in a magnetic field. In *Problems of Analytical Mechanics and the Theories of Stability and Control*. Nauka, Moscow, 47–54 (together with A. A. Khentov).

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## 1976

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## 1977

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*Essays on the Motion of Cosmic Bodies*. Nauka i Izkustvo, Sofiya, 1977.

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The linear problem of the stabilization of biped walking. *Izv. Akad. Nauk SSSR. MTT*, 6, 65–74 (together with P. S. Chudinov).

Asymptotic methods in solid-state dynamics. In *Problems of the Asymptotic Theory of Non-linear Vibrations*. Naukova Dumka, Kiev, 42–46.

Control of biped walking. Preprint No. 10, Institute of Applied Mathematics, USSR Acad. Sci., Moscow. (together with P. S. Chudinov).

## 1978

Some problems of the mechanics of space flight. In *Proc. 4th All-Union Congr. on Theoretical and Applied Mechanics*, Senior Ed. G. S. Pisarenko Naukova Dumka, Kiev, 103–115.

Tidal evolution of the inclinations and rotations of celestial bodies. Preprint No. 43, Institute of Applied Mathematics, USSR Acad. Sci., Moscow.

A non-linear model of a biped walking apparatus with controllable stops. Preprint No. 54, Institute of Applied Mathematics, USSR Acad. Sci., Moscow. (together with V. Ye. Berbyuk).

## 1979

Uncomfortable walking of a biped walking apparatus. *Izv. Akad. Nauk SSSR. MTT*, 3, 46–51 (together with T. S. Kirsanova).

Simulation of walking in zero gravity. *Izv. Akad. Nauk SSSR. MTT*, 48–53 (together with N. S. Konikova).

The principle of comfort in the dynamics of biped walking. *Vestn. MGU. Ser. 1. Matematika, Mekhanika*, 4, 64–68 ((together with Ye. D. Kovaleva and D. Yu. Pogorelov).

Plane resonance rotations of a satellite in an elliptic orbit. *Prikl. Mat. Mekh.* 43, 3, 401–410 (together with D. Yu. Pogorelov).

The problem of the standing of a walking apparatus. *Prikl. Mat. Mekh.* 43, 4, 591–601 (together with E. K. Lavrovskii).

The model problem of the dynamics of underwater biped walking. In *Dynamics of Controlled Systems*. Senior Eds V. M. Matrosov and S. V. Yeliseyev. Nauka, Novosibirsk, 40–48 (together with V. V. Golubkov and Ye. A. Stepanova).

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The set of comfortable gaits of a biped walking apparatus. Preprint No. 25, Institute of Applied Mathematics, USSR Acad. Sci., Moscow. (together with T. S. Kirsanova and E. K. Lavrovskii).

Model problems of the dynamics of underwater biped walking. Preprint No. 42, Institute of Applied Mathematics, USSR Acad. Sci., Moscow, (together with V. V. Golubkov and Ye. A. Stepanova).

Theory of the rotation of Venus. Preprint No. 75, Institute of Applied Mathematics, USSR Acad. Sci., Moscow. (together with Ye. M. Levin and D. Yu. Pogorelov).

Probability investigation of the time of passive stabilization of a satellite. Preprint No. 94, Institute of Applied Mathematics, USSR Acad. Sci., Moscow, (together with D. Yu. Pogorelov).

Problems of the optimization of the dynamics of biped walking. Preprint No. 98, Institute of Applied Mathematics, USSR Acad. Sci., Moscow. (together with A. G. Orlov).

## 1980

Motion control of biped walking robots. In *Automatic Control in Space. 8th IFAK Symp.*, 1979, Ed. C. W. Munday. Pergamon Press, Oxford, 317–322.

The problem of the resonance rotation of Venus. *Astronaut. Zh.* 57, 1, 158–167 (together with Ye. M. Levin and D. Yu. Pogorelov).

Extremal properties of resonance motions. *Dokl. Akad. Nauk SSSR* 251, 1, 58–62 (together with G. V. Kasatkin).

Control of the motion of biped walking apparatus. *Izv. Akad. Nauk SSSR. MTT*, 3, 30–38 (together with P. S. Chudinov).

Mechanics of an orbital tether system. *Kosmich. Issled.* 18, 5, 678–688 (together with Ye. M. Levin).

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## 1981

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The problem of the resonance rotation of Venus. II. *Astronaut. Zh.* 58, 1, 198–207 (together with Ye. M. Levin and D. Yu. Pogorelov).

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Model problem of biped walking. *Izv. Akad. Nauk SSSR. MTT*, 2, 156–165 (together with E. K. Lavrovskii).

Steady motions of an orbital tether system. In *Proc. 4th Joint Scientific Readings on Astronautics, Devoted to the Memory of the Outstanding Pioneering Soviet Scientists Involved in the Conquest of Space. Applied Celestial Mechanics and Control of Motion*. USSR Acad. Sci., Moscow, 115–126 (together with Ye. M. Levin).

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Tidal evolution of inclinations and rotations of celestial bodies. *Celest. Mech.* **23**, 4, 371–382.

The construction of reference solutions in problems of control a biped walking apparatus. *Vestn. MGU. Ser. I. Matematika, Mekhanika*, **6**, 100–103 (together with V. A. Samsonov and O. B. Buzurool).

Some problems in the mechanics of spaceflight. In *Advances in Theoretical and Applied Mechanics*. Eds A. Ishlinsky and F. Chernous, ko. Mir, Moscow, pp. 65–76.

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Energetics of spatial biped walking. Preprint No. 118, Institute of Applied Mathematics, USSR Acad., Moscow (together with Yu. V. Bolotin).

## 1982

Investigation of comfortable modes of motion of a biped apparatus. In *Research on Robotic Systems*. Nauka, Moscow, 195–216 (together with E. K. Lavrovskii).

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